Interrelationships of the North Atlantic multidecadal climate variability characteristics

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Abstract

The North Atlantic is one of the key regions, where low-frequency climate variability is formed. However, despite numerous studies related to this topic, some issues still remains unsolved. One of them is the ambiguous cross-correlation of the North Atlantic sea surface temperature (SST) and the intensity of Atlantic Meridional Overturning Circulation (AMOC). A widely accepted concept suggests that the longterm climate variability is a result of the atmospheric stochastic forcing transformed by the inertial ocean. Existence of negative and positive feedback mechanisms suggests that the long-term North Atlantic dynamics may be considered as a damped stochastically forced oscillator in which both SST and AMOC are the elements of the same process. In this study, we analyze the cross-correlation functions of the main North Atlantic climatic indexes derived from a simple box-like stochastic model. The random forcing simulates the air-sea interface heat fluxes and excites both the SST and the AMOC. Stochastic excitation of the meridional circulation implies the leading AMOC and stochastic forcing of SST implies the leading Atlantic Multidecadal Oscillation (AMO). Connection of the AMOC and AMO indexes depends on the principal oceanic feedbacks and the dissipation intensity.

KEYWORDS: North Atlantic; stochastic forcing; variability; Atlantic Multidecadal Oscillation; cross-correlation

Introduction

One of the key regions where the climate multidecadal variability (MDV) originates is the North Atlantic. The most impressive example of long-term changes may be related to the Atlantic Multidecadal Oscillation. The AMO index is defined by spatially averaged detrended anomalies of the North Atlantic SST [Enfield et al., 2001; Knight et al., 2005, 2006]. However, there are some studies which use slightly different AMO definition, e.g. [d'Orgeville and Peltier, 2007; Trenberth and Shea, 2006].

The North Atlantic SST variability is closely connected to dynamics of the largescale oceanic components, such as AMOC and Subpolar Gyre (SPG). The AMOC plays an important role in the meridional oceanic heat transfer. The largest Atlantic meridional energy transport reaches ~1.2 PW across 26°N [Johns et al., 2011; Ushakov and Ibrayev, 2018].

The leading role of low-frequency variability with the scale of 50-80 years in the North Atlantic climate system was found in [Schlesinger and Ramankutty, 1994; Enfield et al., 2001; Polyakov et al., 2010]. Modeling experiments by Delworth and Mann [2000] showed the pronounced 7-8 decades spectral maxima. Spectral analysis led Wei and Lohmann [2012] to similar conclusions. Wouters et al. [2012] found the dominance AMOC variability with a scale of 50-60 years. Frankcombe and Dijkstra [2011] and Frankcombe et al. [2010] analyzing the 500-years GFDL CM 2.1 control experiments have shown two broad extremes of variability on the time scales of 2-3 and 5-7 decades. Chylek et al. [2012] came to similar results analyzing the isotope δ^{18} O samples of the Greenland ice sheet drilling. MDV of the AMOC index covers the time range from 50 to 200 years [Danabasoglu et al., 2012]. Using the Kiel Climatic Model experiments Ba et al. [2013] analyzed the AMOC and AMO indexes and showed a roughly 60-year oscillation mode. Empirical Mode Decomposition of the AMO time series also demonstrated the prevalence of MDV [Chen et al., 2016]. The same conclusions follow from the analysis of the North Atlantic SST and turbulent surface heat fluxes [Gulev et al., 2013].

In spite of the well-established leading role of the MDV, frequency structure of the North Atlantic climatic indexes still remains ambiguous. Moreover, the existence of spectrum extremes seems doubtful [Cane et al., 2017]. For example, Medhaug and Furevik [2011] found no statistically significant spectral maxima in the AMO and AMOC time series derived from CMIP3 model runs. The same indexes calculated using CMIP5 experiments also demonstrated an absence of the spectral density maxima in any frequency ranges [Zhang and Wang, 2013]. Analysis of the AMO variability by Ba et al. [2014] and Clement et al. [2015] confirmed these conclusions. Multidecadal and multicentury AMO variability studied by Park and Latif [2008] and Dommenget and Latif [2008] showed the spectral density continuum without pronounced extremes. Lack of the spectral maxima can be explained as a feature of the nonlinear chaotic dynamics or as a linear transform of a stochastic external forcing.

The possible mechanisms of the MDV were in a focus of numerical studies. Several hypotheses explaining mechanisms of the MDV have been proposed. One of them associates the formation of MDV with long-term external forcing, first of all to the aerosol of volcanic origin [Ottera et al., 2010; Booth et al., 2012]. However, this idea was criticized later by Zhang et al. [2013] who showed that historical forcing was too weak to serve as the main driver of MDV. Alternative point of view was outlined by Bellomo et al. [2018] who stressed the prevailing role of external factors at the timescale from two decades and longer.

The other concept suggests the leading role of nonlinear processes in the oceanatmosphere system [Dijkstra and Ghil, 2005; Dijkstra et al., 2008]. The proposed mechanism assumes the existence of two quasi-stable stationary states of the Atlantic thermohaline circulation [Cessi, 1994; Rahmstorf, 1995] or SPG [Born and Stocker, 2014; Born et al., 2015]. Dynamical coupling between the atmospheric and oceanic circulation can serve as an alternative mechanism responsible for the low-frequency climate variability [Wills et al., 2019]. Finally, the most accepted hypothesis explains the formation of MDV via response of the highly inertial ocean system to the random atmospheric forcing [Clement et al., 2015, O'Reilly et al., 2016].

The circuit of several cause-and-effect feedbacks argues in favor of describing the process as a damped oscillator [Park and Latif, 2010; Sevellec and Huck, 2015]. Intensification of the AMOC means the advection of warm waters into the northern part

of the North Atlantic, which leads to the positive AMO phase. Warm SST anomalies in the subpolar North Atlantic region prevent deep winter convection. Weakening of the deep water formation leads to the AMOC decrement. Corresponding deficit of the meridional heat transport implies in turn the development of negative SST anomalies and transition to the negative AMO phase. Cold surface waters in the region of Greenland and Labrador seas initiate formation of the deep waters and increase of the AMOC.

The majority of the Coupled General Circulation Models (GCM) experiments demonstrated that the AMOC index leads AMO by several years. As a rule, the indexes are positively correlated at zero time lag. Gastineau et al. [2016] analyzed the control IPSL-CM5A-LR 500-year climate run and found that the cross-correlation is positive with AMOC leading AMO by 5-12 year. The correlation $r \approx 0.42$ is maxima with the time lag of 8 years. van Oldenborgh et al. [2009] and Sun et al. [2015] obtained similar estimate of the AMOC and AMO pair correlation, $r \approx 0.55 \div 0.60$, analyzing the GCM simulations. On the other hand, the COSMOS model generated the AMOC and AMO indexes changing almost in phase [Wei and Lohmann, 2012]. For five CMIP3 model runs the AMOC-AMO correlation coefficient ranges between 0.1 and 0.5, with the strongest correlation found when AMOC leads AMO by 0 to 3 years [Day et al., 2012]. Roberts et al. [2013] investigated 10 CMIP5 model runs and demonstrated similar results. The highest correlation was found when AMOC leads by 1-5 years.

However, there is much complexity in the analysis of the AMOC-AMO connections. The cross-spectral analysis carried out by Marini and Frankignoul [2014] displayed that the low-frequency AMOC and AMO indexes variability resides in phase. Contrary, the phase shift between the two indexes in the model IPSLMC5 was close to 180° [Marini and Frankignoul, 2014]. The estimates derived from 26 CMIP5 models [Muir and Fedorov, 2015] revealed large scatter of the AMOC and AMO characteristics. Zhang and Wang [2013], Wang and Zhang [2013] demonstrated the ambiguous AMOC and AMO relationship, when the correlation in some cases was negative.

What causes the uncertain AMOC-AMO interconnections? Tandon and Kushner [2015], analysing the CMIP3 and CMIP5 control and historical runs, suggested that the external atmospheric forcing can destroy the dynamical AMOC-AMO relationships. As a rule, the leading role belongs to the AMOC. An increase of the AMOC index initiates the positive SST anomalies in the subpolar North Atlantic region. However, when an external forcing switches the scenario, the AMO takes the leading role. Now the SST increase induces attenuation of the meridional thermohaline circulation and the correlation of the two indexes becomes negative.

In this study we further develop the idea of Tandon and Kushnir [2015]. We hypothesize that the atmospheric random forcing is responsible for the MDV formation. In that, the leading role of AMOC is determined by the oceanic system feedbacks. The heat fluxes at the air-sea interface can impact both SST and meridional overturning circulation via intensification of the deep oceanic convection. In case of random excitation of the meridional circulation, the AMOC and AMO indexes are positively correlated. However, the stochastic atmospheric forcing affecting the SST means that correlation between the indexes changes to negative. Theoretical justification of this hypothesis is in the focus of this study.

In the second section, we describe the box stochastic model of the North Atlantic. The third section is devoted to cross-correlation analyses of the model. Finally, we discuss the results and draw the conclusions.

2. A simple North Atlantic model

Legatt et al., [2012] formulated a box North Atlantic model. Built on the Marshall et al., 2001 concept, the model associates the excitation of low-frequency oceanic variability with stochastic atmospheric forcing which is spatially coherent. The main role in the forcing belongs to the North Atlantic Oscillation (NAO) strongly impacting the deep winter convection [McCarthy et al., 2015]. On the other hand, NAO also controls the energy exchange between the ocean and the atmosphere forming the large-scale SST anomalies.

Legatt et al., [2012] suggested that the principal factors forming the North Atlantic MDV include the meridional ψ_m and horizontal ψ_g components of stream function, and the spatially averaged subpolar North Atlantic SST T. The intensities of ψ_m and T can serve as the analogues of AMOC and AMO indexes, respectively. We have modified Legatt et al., [2012] model constraining it for simplicity to two equations. In that, the horizontal component of the stream function was neglected. Besides, the dissipative term was added to the evolutionary equation of the meridional steam function. The dimensionless model equations can be written as

$$\frac{dT}{dt} = m\psi_m - \lambda T + F_T(t), \qquad (1)$$

$$\frac{d\psi_m}{dt} = -sT - \alpha\psi_m + F_m(t), \qquad (2)$$

where $F_T(t)$ is the atmospheric forcing determined by the net heat surface fluxes, $F_m(t)$ is the forcing responsible for the deep water formation and AMOC intensification. We assume the external forcing as a linear function of a stationary Gaussian random process $X(t) = \frac{\partial W}{\partial t}$ (the derivative of the standard Wiener process, W); $F_T(t) = \sigma_{F_T} X(t)$ and $F_m(t) = -\sigma_{F_m} X(t)$, where $\sigma_{F_T}^2$ and $\sigma_{F_m}^2$ are variances of the corresponding fluxes. The negative sign in the last relationship is due to the fact that surface heating of the North Atlantic waters damps the deep oceanic convection. The coefficients λ and α describe the heat and impulse dissipation, respectively; the parameters m and s are positive and simulate the AMOC-AMO linear feedbacks. Unit of the dimensionless time corresponds to ~4 years of physical time, the product $ms \approx 3$, [Legatt et al., 2012]. Note, that the heat fluxes are considered positive when energy is gained by the ocean (in contrast to [Gulev et al., 2013]).

In general, the model formulation assumes that the main peculiarities of the North Atlantic climate variability can be described in the framework of randomly exited damped oscillator.

3. Correlation and cross-correlation analyses of AMO and AMOC

3.1. Stochastic forcing of the meridional thermohaline circulation

In the event of the non-zero meridional thermohaline circulation forcing, i.e. $F_m(t) \neq 0$, $F_T(t) = 0$, the equation for SST takes the form of the linear damping oscillator

$$\frac{d^2T}{dt^2} + 2a\frac{dT}{dt} + bT = mF_m(t), \qquad (3)$$

$$\frac{d\psi_m}{dt} = -sT - \alpha\psi_m + F_m(t).$$
(4)

The coefficients are defined as

$$2a = \alpha + \lambda, \ b = ms + \alpha \lambda. \tag{5}$$

This way, the evolution of the SST is described by the linear differential equation of the second order with a stochastic forcing. The statistically stable solutions of Eqns. (3) and (4) under the assumptions of a > 0 and $b - a^2 > 0$ yields (see e.g. [Yaglom, 1987])

$$T(t) = \int_{0}^{\infty} h_{T}(u) F_{m}(t-u) du,$$
 (6)

where $h_T(u)$ is weight function

$$h_T(u) = \frac{m}{\beta} \exp(-au) \sin(\beta u), \qquad (7)$$

$$\beta = \sqrt{b - a^2} , \qquad (8)$$

$$\psi_m(t) = \int_0^\infty \exp(-\alpha u) (-sT(t-u) + F_m(t-u)) du.$$
(9)

After simplifications (see Appendix 1 for details), Eqn. (9) can be presented in the form of the Duhamel integral

$$\psi_m(t) = \int_0^\infty h_m(u) F_m(t-u) du, \qquad (10)$$

where $h_m(u)$ is a weight function

$$h_m(u) = \exp(-\alpha u) +$$

$$+\frac{ms(-\exp(-\alpha u)\beta + \exp(-\alpha u)[\beta\cos(\beta u) + (\alpha - \alpha)\sin(\beta u)])}{\beta((\alpha - \alpha)^2 + \beta^2)}$$
(11)

The correlation and cross-correlation functions can be written (see Appendix 2, equation B.4) as

$$B_{\rm T}(\tau) = \sigma_{F_m}^2 \int_0^\infty h_T(\xi) h_T(\xi + \tau) d\xi, \qquad (12)$$

$$B_{\psi_m}(\tau) = \sigma_{F_m}^2 \int_0^\infty h_m(\xi) h_m(\xi + \tau) d\xi.$$
(13)

$$B_{\mathrm{T},\psi_m}(\tau) = \sigma_{F_m}^2 \int_{0}^{\infty} h_T(\xi) h_m(\xi + \tau) d\xi \,.$$
(14)

The weight functions (7) and (11) allow analytical integration of the Eqns. (12-14). The correlation functions can be presented in the following normalized form

$$r_{T}(\tau) = \frac{B_{T}(\tau)}{Var[T]} = \exp(-a|\tau|) \left(\cos(\beta\tau) + \frac{a}{\beta}\sin(\beta|\tau|)\right),$$
(15)
$$r_{\psi_{m}}(\tau) = \frac{B_{\psi_{m}}(\tau)}{Var[\psi_{m}]} = \frac{\exp(-a|\tau|) \left(\beta\left(b+\lambda^{2}\right)\cos(\beta\tau) - a\left(b-\lambda^{2}\right)\sin(\beta|\tau|)\right)}{\beta\left(b+\lambda^{2}\right)},$$
(16)

Note, that only random process T(t) is differentiable.

The variances of SST and the meridional component of stream function are defined as

$$Var[T] = \frac{\sigma_m^2 m^2}{4a(\beta^2 + a^2)} = \frac{\sigma_m^2 m^2}{4ab},$$
(17)

$$D[\psi_m] = \frac{\sigma_m^2 \left(b + \lambda^2 \right)}{4ab} \,. \tag{18}$$

The normalized cross-correlation function of T(t) and $\psi_m(t)$ can be written

$$r_{T,\psi_m}(\tau) = \frac{\exp(-a|\tau|) \left(2\beta\lambda\cos(\beta\tau) - 2b\sin(\beta\tau) + \lambda(\alpha+\lambda)\sin(\beta|\tau|) \right)}{2\beta\sqrt{b+\lambda^2}}.$$
 (19)

The normalized cross-correlation function at the zero time lag, $\tau = 0$ is described by the relationship

$$r_{T,\psi_m}(\tau=0) = \frac{\lambda}{\sqrt{b+\lambda^2}} \,. \tag{20}$$

Positive correlation of T(t) and $\psi_m(t)$ is found in many estimates derived from the GCM numerical simulations. However, the magnitude of the correlation coefficient $r_{T,\psi_m}(0)$ can be relatively modest suggesting that the GCM-based estimates of $r_{T,\psi_m}(0)$ cannot serve as a strong argument in the AMOC-AMO interrelationship discussion. The derivative of the cross-correlation function by the zero lag, is always negative

$$\frac{dr_{T,\psi_m}}{d\tau}\Big|_{\tau=0} = \frac{-b}{\sqrt{b+\lambda^2}} \,. \tag{21}$$

Analysis of the formula (19) provides simple equation defining the time delay corresponding to the largest AMO-AMOC correlation

$$\tau_{ex} = \frac{-\arccos\left(\frac{\alpha + 3\lambda}{2\sqrt{ms + 2\lambda(\alpha + \lambda)}}\right)}{\beta}$$
(22)

Applying the parameters values ms = 3, $\alpha = \lambda = 0.5$ one can obtain an estimate of dimensionless time $\tau_{ex} \approx -0.6$. It corresponds approximately to 2.5 years and, therefore, is in agreement with the GCM simulations (e.g. [Day et al., 2012; Roberts et al., 2013]).

3.2. Stochastic forcing of the SST

The second choice for stochastic atmospheric forcing is the direct excitation of the SST. For the sake of simplicity, we will consider here the case when, $F_T(t) \neq 0$, $F_m(t) = 0$. The normalized correlation functions and variances of the SST and the meridional component of stream function (we apply here upper asterisk to distinguish from the random excitation of the stream function ψ_m) can be represented now as

$$r_{T}^{*}(\tau) = \frac{\exp(-a|\tau|)\left[\left(b+\alpha^{2}\right)\beta\cos\left(\beta\tau\right) - a\left(b-\alpha^{2}\right)\sin\left(\beta|\tau|\right)\right]}{\left(b+\alpha^{2}\right)\beta}.$$
(23)

$$r_{\psi_m}^*(\tau) = \exp\left(-a\left|\tau\right|\right) \left(\cos\left(\beta\tau\right) + \frac{a}{\beta}\sin\left(\beta\left|\tau\right|\right)\right).$$
(24)

$$Var^{*}[T] = \frac{\sigma_{T}^{2}(b+\alpha^{2})}{4ab}.$$
(25)

$$Var^* \left[\psi_m(t) \right] = \frac{\sigma_T^2 s^2}{4ab} \,. \tag{26}$$

The normalized cross-correlation function takes the form

$$r_{T,\psi_m}^*(\tau) = \frac{-\exp(-a|\tau|)(2\alpha\beta\cos(\beta\tau) + 2b\sin(\beta\tau) + \alpha(\alpha+\lambda)\sin(\beta|\tau|))}{2\sqrt{b+\alpha^2}\beta}.$$
 (27)

Analysis of the last equation shows that at zero time lag the pair correlation of T and ψ_m is always negative

$$r_{T,\psi_m}^*(0) = \frac{-\alpha}{\sqrt{b+\alpha^2}}.$$
 (28)

Stochastic forcing of the meridional overturning circulation leads to a positive synchronous AMOC-AMO correlation. On the contrary, stochastic forcing of the SST leads to a negative regression. The magnitude of the coefficient can be small and its analysis based on relatively short time series may be problematic. On the other hand, for any stochastic forcing (see also equation 21) the derivative of the cross-correlation function is negative

$$\frac{dr_{T,\psi_m}^*}{d\tau}\Big|_{\tau=0} = \frac{-b}{\sqrt{b+\alpha^2}}.$$
(29)

4. Discussion

Some important properties of the North Atlantic MDV can be described in the stochastic model framework (Eqs. (1-2)). Particularly, the sign of AMOC-AMO correlation depends on the nature of external forcing. The stochastic excitation of the meridional overturning circulation leads to a positive correlation; the SST random forcing leads to a negative correlation. However, the AMOC-AMO correlation is modest at zero time lag.

The excitation of the meridional overturning circulation in the case of moderate negative time delays τ leads to a positive correlation of T(t) and $\psi_m(t)$ (Figure.1). That provides evidence for AMOC leading role, similar to the results of Sun et al., [2018]. The examples of $r_{T,\psi_m}(\tau)$ for several different sets of parameters (Figure 1. a-d) demonstrate that behaviour of the cross-correlation function is determined by the values of dissipation parameters α and λ . Figure 1 a corresponds to e-folding time of 4 dimensionless time units or, respectively, to 16 years and is characterised by slowly decaying oscillating behaviour. Increase of the dissipation parameter α and λ leads to faster decay of oscillations (Figure 1 b c d).

The SST stochastic excitation is characterised by important distinctions of crosscorrelation function. A comparison between $r_{T,\psi_m}^*(\tau)$ and $r_{T,\psi_m}(\tau)$ reveals some interesting features. For example, if the dissipation parameters α and λ are small then the behaviour of $r_{T,\psi_m}^*(\tau)$ and $r_{T,\psi_m}(\tau)$ is similar (Figure 1 a b). Increase of α and λ results in significantly different dependences of $r_{T,\psi_m}^*(\tau)$ and $r_{T,\psi_m}(\tau)$ on time delay τ (Figure 1, c and d). The strongest negative cross-correlation $r_{T,\psi_m}^*(\tau)$ is observed at the positive time lags. Now the cross-correlation functions $r_{T,\psi_m}^*(\tau)$ can be interpreted as evidence for the leading role of the AMO. The positive SST anomalies prevent deep water formation and damp the meridional oceanic circulation.

We note that caution should be exercised when interpreting the results of the crosscorrelation analysis of the observational and/or GCM modeling data. Often the interpretation of this analysis and especially establishment of the cause-effect relationships seems doubtful and ambiguous. Besides, limited and, as a rule, strongly auto-correlated time series of GCM simulations often cannot guarantee statistically significant estimates. As a consequence, establishment of the physically-based conclusions requires formulation of an adequate background model.

5. Conclusions

1. Some important properties of the North Atlantic MDV can be reproduced within the stochastically forced oceanic oscillator model. Stochastic excitation of the meridional overturning circulation corresponds to a positive synchronous AMOC-AMO correlation, random forcing of the SST leads to a negative correlation. These differences can explain some discrepancies of the correlation analyses made in the past using GCM outputs.

2. Stochastic excitation of the meridional overturning circulation implies the leading AMOC and stochastic forcing of SST implies the leading AMO. However, in both cases the time derivative of AMOC and AMO cross-correlation function is always negative at zero time lag.

3. Significant effect of the e-folding time on the AMOC-AMO interrelationship has been found. Cross-correlation function demonstrates highly oscillating behaviour in the case of relatively small dissipation coefficients. Decrease of the e-folding time is characterized by almost monotonous decay of the cross-correlation function.

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Appendix 1

Using the expression (6) and change of variables, $\xi + u = t'$, we can transform equation (9)

$$\psi_m(t) = -sm \int_0^\infty \exp(-\alpha\xi) \int_{\xi}^\infty h_T(t'-\xi) F_m(t-t') dt' d\xi + \int_0^\infty \exp(-\alpha\xi) F_m(t-\xi) d\xi =$$

$$= -\frac{sm}{\beta} \int_0^\infty \exp(-\alpha\xi) \int_{\xi}^\infty \exp(-\alpha(t'-\xi)) \sin(\beta(t'-\xi)) F_m(t-t') dt' d\xi +$$

$$+ \int_0^\infty \exp(-\alpha\xi) F_m(t-\xi) d\xi.$$
(A.1)

The trigonometric identities allow rewriting (A.1) as

$$\psi_{m}(t) = -\frac{sm}{\beta} \int_{0}^{\infty} \exp((a-\alpha)\xi) \cos(\beta\xi) \int_{\xi}^{\infty} \exp(-at') \sin(\beta t') F_{m}(t-t') dt' d\xi + \frac{sm}{\beta} \int_{0}^{\infty} \exp((-\alpha + a)\xi) \sin(\beta\xi) \int_{\xi}^{\infty} \exp(-at') \cos(\beta t') F_{m}(t-t') dt' d\xi + \int_{0}^{\infty} \exp(-\alpha\xi) F_{m}(t-\xi) d\xi.$$
(A.2)

Now we can integrate (A.2) by part. After some simplifications (A.2) can be presented in the form of Duhamel integral

$$\psi_m(t) = \int_0^\infty h_m(u) F_m(t-u) du, \qquad (A.3)$$

where $h_m(u)$ is a weight function

$$h_{m}(u) = \exp(-\alpha u) + \frac{ms(-\exp(-\alpha u)\beta + \exp(-\alpha u)[\beta\cos(\beta u) + (\alpha - \alpha)\sin(\beta u)])}{\beta((\alpha - \alpha)^{2} + \beta^{2})}$$
(A.4)

Appendix 2

Let us represent the solutions for the two components Y(t) and Z(t) of the stochastically forced differential equation system in the form of Duhamel integrals

$$Y(t) = \int_{0}^{\infty} h_Y(u) X(t-u) du,$$

$$Z(t) = \int_{0}^{\infty} h_Z(u) X(t-u) du,$$
 (B.1)

where $h_Y(t)$ and $h_Z(t)$ are the weight functions of the Y(t) and Z(t), respectively. The input signal X(t) represents stationary stochastic process and is characterized by the correlation function $B_X(\tau)$. In the assumptions M[Y(t)] = M[Z(t)] = 0 crosscorrelation function of the Y(t) and Z(t) can be written as

$$B_{Y,Z}(\tau) = M \left[Y(t)Z(t+\tau) \right] =$$
$$= M \left[\int_{0}^{\infty} \int_{0}^{\infty} h_Y(\xi) X(t-\xi) h_Z(\eta) X(t+\tau-\eta) d\eta d\xi \right] =$$

$$= \int_{0}^{\infty} h_{Y}(\xi) \int_{0}^{\infty} h_{Z}(\eta) B_{X}(\tau + \xi - \eta) d\eta d\xi.$$
(B.2)

Using Parseval's theorem we can write (Bekryaev, 2016) cross-correlation function in the form of convolution integral

$$B_{Y,Z}(\tau) = \int_{-\infty}^{\infty} B_X(s) \int_{0}^{\infty} h_Y(\xi) h_Z(\xi + s + \tau) d\xi ds$$
(B.3)

If the input process X(t) is a derivative of the standard Wiener process, W(t), i.e. ($X(t) = \sigma_x^2 \frac{dW}{dt}$), equation (A.3) can be represented in a form

$$B_{Y,Z}(\tau) = \sigma_X^2 \int_0^\infty h_Y(\xi) h_Z(\xi + \tau) d\xi.$$
(B.4)

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a) $\alpha = \lambda = 0.25$, b) $\alpha = \lambda = 0.5$, c) $\alpha = \lambda = 1.0$, d) $\alpha = \lambda = 2.0$.

The parameter values $\alpha = \lambda = 0.5$ corresponds to e-folding time equal to 2 units of dimensionless time and, respectively, to 8 years.